## 19-1760; Rev 1; 2/02 EVALUATION KIT AVAILABLE 1A/2.7A, 1MHz, Step-Down Regulators with Synchronous Rectification and Internal Switches

## **General Description**

The MAX1742/MAX1842 constant-off-time, pulse-widthmodulated (PWM) step-down DC-DC converters are ideal for use in 5V and 3.3V to low-voltage conversion necessary in notebook and subnotebook computers. These devices feature internal synchronous rectification for high efficiency and reduced component count. They require no external Schottky diode. The internal 90m $\Omega$  PMOS power switch and 70m $\Omega$  NMOS synchronous-rectifier switch easily deliver continuous load currents up to 1A. The MAX1742/MAX1842 produce a preset 2.5V, 1.8V, or 1.5V output voltage or an adjustable output from 1.1V to VIN. They achieve efficiencies as high as 95%.

The MAX1742/MAX1842 use a unique current-mode, constant-off-time, PWM control scheme, which includes Idle Mode<sup>™</sup> to maintain high efficiency during light-load operation. The programmable constant-off-time architecture sets switching frequencies up to 1MHz, allowing the user to optimize performance trade-offs between efficiency, output switching noise, component size, and cost. Both devices are designed for continuous output currents up to 1A. The MAX1742 uses a peak current limit of 1.3A (min) and is suitable for applications requiring small external component size and high efficiency. The MAX1842 has a higher current limit of 3.1A (min) and is intended for applications requiring an occasional burst of output current up to 2.7A. Both devices also feature an adjustable soft-start to limit surge currents during startup, a 100% duty cycle mode for low-dropout operation, and a low-power shutdown mode that disconnects the input from the output and reduces supply current below 1µA. The MAX1742/MAX1842 are available in 16pin QSOP packages.

For similar devices that provide continuous output currents up to 2A and 3A, refer to the MAX1644 and MAX1623 data sheets.

## Applications

5V or 3.3V to Low-Voltage Conversion CPU I/O Ring Chipset Supplies Notebook and Subnotebook Computers

Pin Configuration appears at end of data sheet.

Idle Mode is a trademark of Maxim Integrated Products.

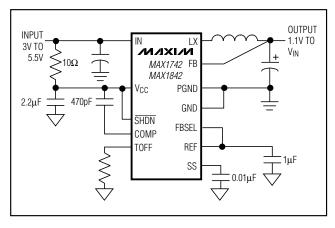
### **Features**

- ±1% Output Accuracy
- ♦ 95% Efficiency
- Internal PMOS and NMOS Switches 90mΩ On-Resistance at V<sub>IN</sub> = 4.5V 110mΩ On-Resistance at V<sub>IN</sub> = 3V
- Output Voltage
  2.5V, 1.8V, or 1.5V Pin Selectable
  1.1V to V<sub>IN</sub> Adjustable
- ♦ 3V to 5.5V Input Voltage Range
- ♦ 600µA (max) Operating Supply Current
- <1µA Shutdown Supply Current</p>
- Programmable Constant-Off-Time Operation
- 1MHz (max) Switching Frequency
- Idle-Mode Operation at Light Loads
- Thermal Shutdown
- Adjustable Soft-Start Inrush Current Limiting
- ♦ 100% Duty Cycle During Low-Dropout Operation
- Output Short-Circuit Protection
- 16-Pin QSOP Package

### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX1742EEE	-40°C to +85°C	16 QSOP
MAX1842EEE	-40°C to +85°C	16 QSOP

## **Typical Configuration**



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For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

## **ABSOLUTE MAXIMUM RATINGS**

V <sub>CC</sub> , IN to GND	-0.3V to +6V	
IN to V <sub>CC</sub>		
GND to PGND		
All Other Pins to GND	0.3V to (V <sub>CC</sub> + 0.3V)	
LX Current (Note 1)	±4.7Á	
REF Short Circuit to GND Duration		
ESD Protection	±2kV	

Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
SSOP (derate 16.7mW/°C above +70°C;	
part mounted on 1 in. <sup>2</sup> of 1oz. copper)	1W
Operating Temperature Range	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

**Note 1:** LX has internal clamp diodes to PGND and IN. Applications that forward-bias these diodes should take care not to exceed the IC's package power dissipation limits.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **ELECTRICAL CHARACTERISTICS**

(VIN = VCC = 3.3V, FBSEL = GND, TA = 0°C to +85°C, unless otherwise noted. Typical values are at TA = +25°C.)

PARAMETER	SYMBOL	CONDITIONS			MIN	ТҮР	МАХ	UNITS
Input Voltage	V <sub>IN</sub> , V <sub>CC</sub>				3.0		5.5	V
		V <sub>IN</sub> = 3V to 5.5V, F I <sub>LOAD</sub> = 0 to 1A for	$FBSEL = to + \epsilon V_{CC} T_{A} =$	$T_A = +25^{\circ}C$ to +85°C	2.500	2.525	2.550	-
				$T_A = +0^{\circ}C$ to +85°C	2.487	2.525	2.563	
			FBSEL = unconnected	$T_A = +25^{\circ}C$ to +85°C	1.500	1.515	1.530	
Preset Output Voltage	Vout			$T_A = +0^{\circ}C$ to +85°C	1.492	1.515	1.538	- V
Freset Output voltage	VOUT	$I_{LOAD} = 0$ to 2.5A for	UAD - U	$T_A = +25^{\circ}C$ to +85^{\circ}C	1.800	1.818	1.836	
		MAX1842, REF VFB = VOUT FBSEL = GND	$T_A = +0^{\circ}C$ to +85°C	1.791	1.818	1.845		
			FBSEL =	$T_A = +25^{\circ}C$ to +85°C	1.089	1.100	1.111	
			GND	$T_A = +0^{\circ}C$ to +85°C	1.084	1.100	1.117	
Adjustable Output Voltage Range		V <sub>IN</sub> = V <sub>CC</sub> = 3 FBSEL = GNE	3V to 5.5V, I <sub>LOAD</sub>	= 0,	V <sub>REF</sub>		V <sub>IN</sub>	V
AC Load Regulation Error						2		%
DC Load Regulation Error						0.4		%
Dropout Voltage	V <sub>DO</sub>	$V_{IN} = V_{CC} = 3$	BV, I <sub>LOAD</sub> = 1A				250	mV
Reference Voltage	V <sub>REF</sub>	$T_A = +25^{\circ}C$ to	$T_A = +25^{\circ}C \text{ to } +85^{\circ}C$		1.089	1.100	1.111	v
helefence voltage	V REF	$T_A = +0^{\circ}C$ to	0°C to +85°C		1.084	1.100	1.117	v
Reference Load Regulation	$\Delta V_{REF}$	$I_{REF} = -1\mu A$ to $+10\mu A$				0.5	2	mV
PMOS Switch On-Resistance	Ron, p	$I_{LX} = 0.5A$		$V_{IN} = 4.5V$ $V_{IN} = 3V$		90 110	200 250	-
NMOS Switch				$V_{IN} = 3V$ $V_{IN} = 4.5V$		70	150	mΩ
On-Resistance	Ron, n	I <sub>LX</sub> = 0.5A		$V_{IN} = 3V$		80	200	

# **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{IN} = V_{CC} = 3.3V, FBSEL = GND, T_A = 0^{\circ}C \text{ to } +85^{\circ}C, unless otherwise noted. Typical values are at T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS	
		MAX1742	1.3	1.5	1.7		
Current-Limit Threshold	ILIMIT	MAX1842	3.1	3.6	4.1	A	
RMS LX Output Current					3.1	А	
Idle Mode Current Threshold	la c	MAX1742	0.1	0.3	0.5	A	
Idle Mode Current Threshold	IМ	MAX1842	0.3	0.6	0.9	A	
Switching Frequency	f	(Note 2)			1	MHz	
No-Load Supply Current	I <sub>IN</sub> + I <sub>CC</sub>	V <sub>FB</sub> = 1.2V		350	600	μA	
Shutdown Supply Current	I <sub>CC</sub> (SHDN)	$\overline{SHDN} = GND$		<1	5	μA	
PMOS Switch Off-Leakage Current	l <sub>IN</sub>	SHDN = GND			15	μA	
Thermal Shutdown Threshold	T <sub>SHDN</sub>	Hysteresis = 15°C		160		°C	
Undervoltage Lockout Threshold	Vuvlo	V <sub>IN</sub> falling, hysteresis = 90mV	2.5	2.6	2.7	V	
FB Input Bias Current	I <sub>FB</sub>	V <sub>FB</sub> = 1.2V	0	60	250	nA	
	tOFF	$R_{TOFF} = 110k\Omega$	0.9	1.00	1.1	μs	
Off-Time Default Period		$R_{TOFF} = 30.1 k\Omega$	0.24	0.30	0.37		
		$R_{TOFF} = 499 k\Omega$	3.8	4.5	5.2		
Off-Time Startup Period	toff	FB = GND		4 × toff		μs	
On-Time Period	ton	(Note 2)	0.4			μs	
SS Source Current	I <sub>SS</sub>		4	5	6	μΑ	
SS Sink Current	I <sub>SS</sub>	$V_{SS} = 1V$	100			μΑ	
SHDN Input Current	ISHDN	$V_{\overline{SHDN}} = 0$ to $V_{CC}$	-1		1	μA	
SHDN Input Low Threshold	VIL				0.8	V	
SHDN Input High Threshold	VIH		2.0			V	
FBSEL Input Current			-4		+4	μA	
		FBSEL = GND			0.2		
		FBSEL = REF	0.9		1.3		
FBSEL Logic Thresholds		FBSEL = unconnected	0.7 × VC - 0.2	C 0.7 +C	7 × VCC ).2	V	
		FBSEL = V <sub>CC</sub>	V <sub>CC</sub> - 0.2			]	

## **ELECTRICAL CHARACTERISTICS**

(VIN = V<sub>CC</sub> = 3.3V, FBSEL = GND, T<sub>A</sub> = -40°C to +85°C, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.) (Note 3)

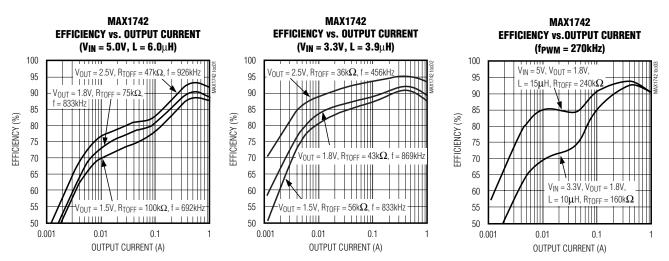
PARAMETER	SYMBOL	CONDITIONS		MIN	MAX	UNITS	
Input Voltage	VIN			3.0	5.5	V	
		$I_{LOAD} = 0$ to 1A for MAX1742,		2.475	2.575		
Preset Output Voltage	Vout	$I_{LOAD} = 0$ to 2.5A	FBSEL = unconnected	1.485	1.545	V	
		for MAX1842,	FBSEL = REF	1.782	1.854		
		V <sub>FB</sub> = V <sub>OUT</sub>	FBSEL = GND	1.078	1.122	]	
Adjustable Output Voltage Range		$V_{IN} = V_{CC} = 3V \text{ to } 5$ FBSEL = GND	$V_{IN} = V_{CC} = 3V \text{ to } 5.5V, I_{LOAD} = 0,$ FBSEL = GND		V <sub>IN</sub>	V	
Reference Voltage	V <sub>REF</sub>				1.122	V	
PMOS Switch	Pourp	I <sub>LX</sub> = 0.5A	$V_{IN} = 4.5V$		200		
On-Resistance	Ron, p	$I_L \chi = 0.5 A$	$V_{IN} = 3V$		250	mΩ	
NMOS Switch	Ron, N	$R_{ON, N}$ $I_{LX} = 0.5A$	$V_{IN} = 4.5V$		150	11152	
On-Resistance	HON, N	ILX = 0.5A	$V_{IN} = 3V$		200		
Current-Limit Threshold	h n n <del>a</del>	MAX1742		1.2	1.8		
	ILIMIT	MAX1842		2.9	4.3	^	
Idle Mode Current Threshold	lu e	MAX1742		0.05	0.55	A	
Idle Mode Current Threshold	IIM	MAX1842		0.2	1.0		
No-Load Supply Current	IIN + ICC	V <sub>FB</sub> = 1.2V			600	μΑ	
FB Input Bias Current	I <sub>FB</sub>	V <sub>FB</sub> = 1.2V		0	300	nA	
Off-Time Default Period	tOFF	$R_{TOFF} = 110 k\Omega$		0.85	1.15	μs	

Note 2: Recommended operating frequency, not production tested.

Note 3: Specifications from 0°C to -40°C are guaranteed by design, not production tested.

(Circuit of Figure 1,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

## **Typical Operating Characteristics**



MAX1742 NORMALIZED OUTPUT ERROR vs. OUTPUT CURRENT 0.5 0.4 NORMALIZED OUTPUT ERROR (%) 0.3 ┼┼┼┼┼  $V_{IN} = 5V, V_{OUT} = 1.5V, L = 6\mu H$ 0.2 0.1 0 -0.1 -0.2 3.3V, V<sub>OUT</sub> = 1 VIN = 5\ -0.3 -0.4 -0.5 0.001 0.01 0.1 1 OUTPUT CURRENT (A)

SWITCHING FREQUENCY vs. OUTPUT CURRENT

1100

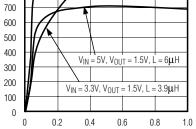
1000

900

800

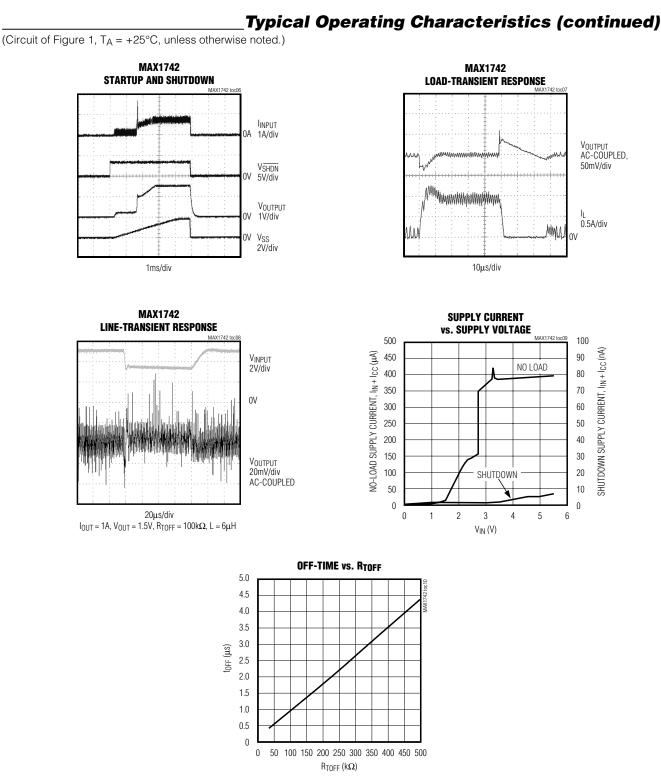
FREQUENCY (kHz)

MAX1742

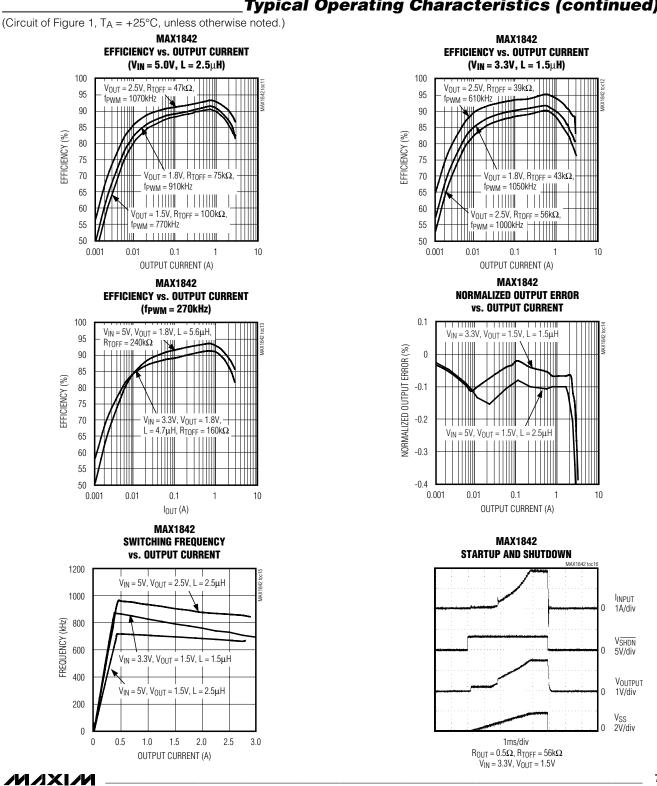


OUTPUT CURRENT (A)

MAX1742/MAX1842

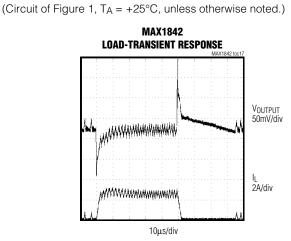


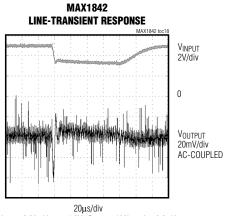
MAX1742/MAX1842



MAX1742/MAX1842

## **Typical Operating Characteristics (continued)**





 $I_{OUT} = 2.5A, V_{OUT} = 1.5V, R_{TOFF} = 100k\Omega, L = 2.2\mu H$ 

# \_Pin Description

PIN	NAME	FUNCTION
1	SHDN	Shutdown Control Input. Drive $\overline{SHDN}$ low to disable the reference, control circuitry, and internal MOSFETs. Drive high or connect to V <sub>CC</sub> for normal operation.
2, 4	IN	Supply Voltage Input—for the internal PMOS power switch.
3, 14, 16	LX	Connection for the drains of the PMOS power switch and NMOS synchronous-rectifier switch. Connect the inductor from this node to the output filter capacitor and load.
5	SS	Soft-Start. Connect a capacitor from SS to GND to limit inrush current during startup.
6	COMP	Integrator Compensation. Connect a capacitor from COMP to V <sub>CC</sub> for integrator compensation. See <i>Integrator Amplifier</i> section.
7	TOFF	Off-Time Select Input. Sets the PMOS power switch off-time during constant-off-time operation. Connect a resistor from TOFF to GND to adjust the PMOS switch off-time.
8	FB	Feedback Input—for both preset-output and adjustable-output operating modes. Connect directly to output for fixed-voltage operation or to a resistive divider for adjustable operating modes.
9	GND	Analog Ground
10	REF	Reference Output. Bypass REF to GND with a 1µF capacitor.
11	FBSEL	Feedback Select Input. Selects output voltage. See Table 3 for programming instructions.
12	Vcc	Analog Supply Voltage Input. Supplies internal analog circuitry. Bypass V <sub>CC</sub> with a 10 $\Omega$ and 2.2µF low-pass filter. See Figure 1.
13, 15	PGND	Power Ground. Internally connected to the internal NMOS synchronous-rectifier switch.

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## **Detailed Description**

The MAX1742/MAX1842 synchronous, current-mode, constant-off-time, PWM DC-DC converters step down input voltages of 3V to 5.5V to a preset output voltage of 2.5V, 1.8V, or 1.5V, or to an adjustable output voltage from 1.1V to V<sub>IN</sub>. Both devices deliver up to 1A of continuous output current; the MAX1842 delivers bursts of output current up to 2.7A (see the *Extended Current Limit* section). Internal switches composed of a 0.09 $\Omega$  PMOS power switch and a 0.07 $\Omega$  NMOS synchronous rectifier switch improve efficiency, reduce component count, and eliminate the need for an external Schottky diode.

The MAX1742/MAX1842 optimize efficiency by operating in constant-off-time mode under heavy loads and in Maxim's proprietary Idle Mode under light loads. A single resistor-programmable constant-off-time control sets switching frequencies up to 1MHz, allowing the user to optimize performance trade-offs in efficiency, switching noise, component size, and cost. Under lowdropout conditions, the device operates in a 100% duty-cycle mode, where the PMOS switch remains continuously on. Idle Mode enhances light-load efficiency by skipping cycles, thus reducing transition and gatecharge losses.

When power is drawn from a regulated supply, constantoff-time PWM architecture essentially provides constantfrequency operation. This architecture has the inherent advantage of quick response to line and load transients.

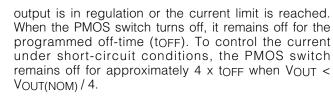
The MAX1742/MAX1842s' current-mode, constant-offtime PWM architecture regulates the output voltage by changing the PMOS switch on-time relative to the constant off-time. Increasing the on-time increases the peak inductor current and the amount of energy transferred to the load per pulse.

#### Modes of Operation

The current through the PMOS switch determines the mode of operation: constant-off-time mode (for load currents greater than half the Idle Mode threshold), or Idle Mode (for load currents less than half the Idle Mode threshold). Current sense is achieved through a proprietary architecture that eliminates current-sensing I<sup>2</sup>R losses.

#### Constant-Off-Time Mode

Constant-off-time operation occurs when the current through the PMOS switch is greater than the Idle Mode threshold current (which corresponds to a load current of half the Idle Mode threshold). In this mode, the regulation comparator turns the PMOS switch on at the end of each off-time, keeping the device in continuous-conduction mode. The PMOS switch remains on until the



#### Idle Mode

Under light loads, the devices improve efficiency by switching to a pulse-skipping Idle Mode. Idle Mode operation occurs when the current through the PMOS switch is less than the Idle Mode threshold current. Idle Mode forces the PMOS to remain on until the current through the switch reaches the Idle Mode threshold, thus minimizing the unnecessary switching that degrades efficiency under light loads. In Idle Mode, the device operates in discontinuous conduction. Currentsense circuitry monitors the current through the NMOS synchronous switch, turning it off before the current reverses. This prevents current from being pulled from the output filter through the inductor and NMOS switch to ground. As the device switches between operating modes, no major shift in circuit behavior occurs.

#### 100% Duty-Cycle Operation

When the input voltage drops near the output voltage, the duty cycle increases until the PMOS MOSFET is on continuously. The dropout voltage in 100% duty cycle is the output current multiplied by the on-resistance of the internal PMOS switch and parasitic resistance in the inductor. The PMOS switch remains on continuously as long as the current limit is not reached.

#### Shutdown

Drive  $\overline{SHDN}$  to a logic-level low to place the MAX1742/MAX1842 in low-power shutdown mode and reduce supply current to less than 1µA. In shutdown, all circuitry and internal MOSFETs turn off, and the LX node becomes high impedance. Drive  $\overline{SHDN}$  to a logic-level high or connect to V<sub>CC</sub> for normal operation.

#### **Summing Comparator**

Three signals are added together at the input of the summing comparator (Figure 2): an output voltage error signal relative to the reference voltage, an integrated output voltage error correction signal, and the sensed PMOS switch current. The integrated error signal is provided by a transconductance amplifier with an external capacitor at COMP. This integrator provides high DC accuracy without the need for a high-gain amplifier. Connecting a capacitor at COMP modifies the overall loop response (see the *Integrator Amplifier* section).





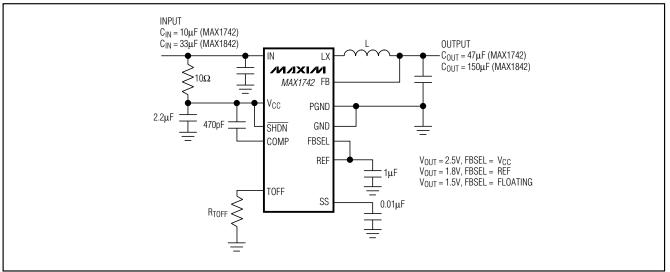


Figure 1. Typical Circuit

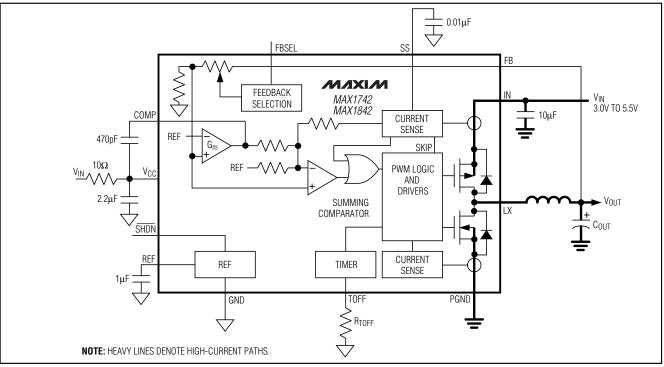


Figure 2. Functional Diagram

#### Synchronous Rectification

In a step-down regulator without synchronous rectification, an external Schottky diode provides a path for current to flow when the inductor is discharging. Replacing the Schottky diode with a low-resistance NMOS synchronous switch reduces conduction losses and improves efficiency.

The NMOS synchronous-rectifier switch turns on following a short delay after the PMOS power switch turns off, thus preventing cross conduction or "shoot through." In



constant-off-time mode, the synchronous-rectifier switch turns off just prior to the PMOS power switch turning on. While both switches are off, inductor current flows through the internal body diode of the NMOS switch. The internal body diode's forward voltage is relatively high.

#### **Thermal Resistance**

Junction-to-ambient thermal resistance,  $\theta_{JA}$ , is highly dependent on the amount of copper area immediately surrounding the IC leads. The MAX1742 evaluation kit has  $0.5in^2$  of copper area and a thermal resistance of  $80^{\circ}$ C/W with no forced airflow. Airflow over the board significantly reduces the junction-to-ambient thermal resistance. For heatsinking purposes, evenly distribute the copper area connected at the IC among the high-current pins.

#### **Power Dissipation**

Power dissipation in the MAX1742/MAX1842 is dominated by conduction losses in the two internal power switches. Power dissipation due to supply current in the control section and average current used to charge and discharge the gate capacitance of the internal switches (i.e., switching losses) is approximately:

#### $P_{DS} = C \times V_{IN}^2 \times f_{PWM}$

where C = 2.5nF and fPWM is the switching frequency in PWM mode.

This number is reduced when the switching frequency decreases as the part enters Idle Mode. Combined conduction losses in the two power switches are approximated by:

#### $P_D = I_{OUT}^2 \times R_{PMOS}$

where RPMOS is the on-resistance of the PMOS switch.

The junction-to-ambient thermal resistance required to dissipate this amount of power is calculated by:

 $\theta_{JA} = (T_{J,MAX} - T_{A,MAX}) / P_{D(TOT)}$ 

where:  $\theta_{JA}$  = junction-to-ambient thermal resistance

T<sub>J,MAX</sub> = maximum junction temperature

TA,MAX = maximum ambient temperature

 $P_D(TOT) = total losses$ 

#### Design Procedure

For typical applications, use the recommended component values in Tables 1 or 2. For other applications, take the following steps:

 Select the desired PWM-mode switching frequency; 1MHz is a good starting point. See Figure 3 for maximum operating frequency.

# Table 1. MAX1742 RecommendedComponent Values (IOUT = 1A)

VIN (V)	Vоит (V)	fpwм (kHz)	L (µH)	<b>В</b> то <b></b> ( <b>k</b> Ω)
5	3.3	850	5.6	39
5	2.5	1070	5.6	47
5	1.8	910	5.6	75
5	1.5	770	5.6	100
3.3	2.5	610	3.9	39
3.3	1.8	1050	3.9	43
3.3	1.5	1000	3.9	56

# Table 2. MAX1842 RecommendedComponent Values (Continuous OutputCurrent = 1A, Burst Output Current = 2.7A)

V <sub>IN</sub> (V)	Vоит (V)	fpwм (kHz)	L (µH)	<b>R</b> тоғғ (kΩ)
5	3.3	800	2.2	39
5	2.5	1180	2.2	47
5	1.8	850	2.2	75
5	1.5	715	2.2	100
3.3	2.5	570	1.5	39
3.3	1.8	985	1.5	43
3.3	1.5	940	1.5	56

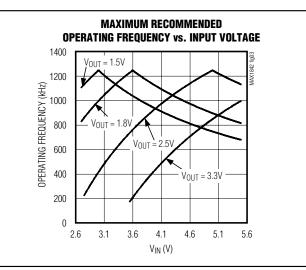


Figure 3. Maximum Recommended Operating Frequency vs. Input Voltage

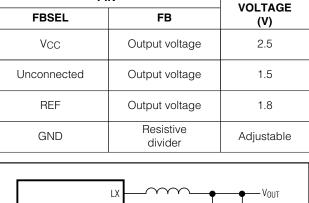


## Table 3. Output Voltage Programming

PIN

1A/2.7A, 1MHz, Step-Down Regulators with

OUTPUT



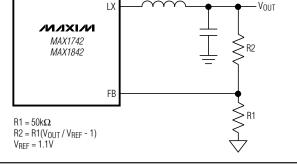


Figure 4. Adjustable Output Voltage

- 2) Select the constant off-time as a function of input voltage, output voltage, and switching frequency.
- 3) Select RTOFF as a function of off-time.
- 4) Select the inductor as a function of output voltage, off-time, and peak-to-peak inductor current.

#### Setting the Output Voltage

The output of the MAX1742/MAX1842 is selectable between one of three preset output voltages: 2.5V, 1.8V, and 1.5V. For a preset output voltage, connect FB to the output voltage and connect FBSEL as indicated in Table 3. For an adjustable output voltage, connect FBSEL to GND and connect FB to a resistive divider between the output voltage and ground (Figure 4). Regulation is maintained for adjustable output voltages when  $V_{FB} = V_{REF}$ . Use 50k $\Omega$  for R1. R2 is given by the equation:

$$R2 = R1 \left( \frac{V_{OUT}}{V_{REF}} - 1 \right)$$

where VREF is typically 1.1V.

#### **Programming the Switching Frequency** and Off-Time

The MAX1742/MAX1842 features a programmable PWM mode switching frequency, which is set by the input and output voltage and the value of RTOFF, connected from TOFF to GND. RTOFF sets the PMOS power switch off-time in PWM mode. Use the following equation to select the off-time according to your desired switching frequency in PWM mode:

$$t_{OFF} = \frac{(V_{IN} - V_{OUT} - V_{PMOS})}{f_{PWM}(V_{IN} - V_{PMOS} + V_{NMOS})}$$

where: tOFF = the programmed off-time

- $V_{IN}$  = the input voltage
- $V_{OUT}$  = the output voltage
- VPMOS = the voltage drop across the internal PMOS power switch
- VNMOS = the voltage drop across the internal NMOS synchronous-rectifier switch
- fpwm = switching frequency in PWM mode

Select RTOFF according to the formula:

RTOFF =  $(tOFF - 0.07\mu s)(110k\Omega / 1.00\mu s)$ 

Recommended values for RTOFF range from  $36k\Omega$  to  $430k\Omega$  for off-times of 0.4µs to 4µs.

#### **Inductor Selection**

The key inductor parameters must be specified: inductor value (L) and peak current (IPEAK). The following equation includes a constant, denoted as LIR, which is the ratio of peak-to-peak inductor AC current (ripple current) to maximum DC load current. A higher value of LIR allows smaller inductance but results in higher losses and ripple. A good compromise between size and losses is found at approximately a 25% ripple-current to load-current ratio (LIR = 0.25), which corresponds to a peak inductor current 1.125 times the DC load current:

$$L = \frac{V_{OUT} \times t_{OFF}}{I_{OUT} \times LIR}$$

where: IOUT = maximum DC load current

LIR = ratio of peak-to-peak AC inductor current to DC load current, typically 0.25



The peak inductor current at full load is 1.125 x IOUT if the above equation is used; otherwise, the peak current is calculated by:

$$I_{PEAK} = I_{OUT} + \frac{V_{OUT} \times t_{OFF}}{2 \times L}$$

Choose an inductor with a saturation current at least as high as the peak inductor current. The inductor you select should exhibit low losses at your chosen operating frequency.

#### **Capacitor Selection**

The input filter capacitor reduces peak currents and noise at the voltage source. Use a low-ESR and low-ESL capacitor located no further than 5mm from IN. Select the input capacitor according to the RMS input ripple-current requirements and voltage rating:

$$I_{\text{RIPPLE}} = I_{\text{LOAD}} \frac{\sqrt{V_{\text{OUT}}(V_{\text{IN}} - V_{\text{OUT}})}}{V_{\text{IN}}}$$

where IRIPPLE = input RMS current ripple.

The output filter capacitor affects the output voltage ripple, output load-transient response, and feedback loop stability. For stable operation, the MAX1742/MAX1842 requires a minimum output ripple voltage of VRIPPI F  $\geq$ 1% x Vout.

The minimum ESR of the output capacitor should be:

$$ESR > 1\% \times \frac{L}{t_{OFF}}$$

Stable operation requires the correct output filter capacitor. When choosing the output capacitor, ensure that:

$$C_{OUT} \ge \frac{t_{OFF}}{V_{OUT}}$$
 33µFV/µs for the MAX1742  
 $C_{OUT} \ge \frac{t_{OFF}}{V_{OUT}}$  79µFV/µs for the MAX1842

#### Integrator Amplifier

An internal transconductance amplifier fine tunes the output DC accuracy. A capacitor, CCOMP, from COMP to V<sub>CC</sub> compensates the transconductance amplifier. For stability, choose  $C_{COMP} = 470 pF$ .

A large capacitor value maintains a constant average output voltage but slows the loop response to changes in output voltage. A small capacitor value speeds up the loop response to changes in output voltage but

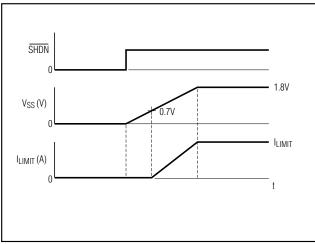


Figure 5. Soft-Start Current Limit over Time

decreases stability. Choose the capacitor values that result in optimal performance.

#### Soft-Start

MAX1742/MAX1842

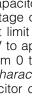
Soft-start allows a gradual increase of the internal current limit to reduce input surge currents at startup and at exit from shutdown. A timing capacitor, CSS, placed from SS to GND sets the rate at which the internal current limit is changed. Upon power-up, when the device comes out of undervoltage lockout (2.6V typ) or after the SHDN pin is pulled high, a 4µA constant-current source charges the soft-start capacitor and the voltage on SS increases. When the voltage on SS is less than approximately 0.7V, the current limit is set to zero. As the voltage increases from 0.7V to approximately 1.8V, the current limit is adjusted from 0 to the current-limit threshold (see the Electrical Characteristics). The voltage across the soft-start capacitor changes with time according to the equation:

$$V_{\rm SS} = \frac{4\mu A \times t}{C_{\rm SS}}$$

The soft-start current limit varies with the voltage on the soft-start pin, SS, according to the equation:

$$SSI_{LIMIT} = \frac{V_{SS} - 0.7V}{1.1V} \times I_{LIMIT}$$

where ILIMIT is the current threshold from the Electrical Characteristics.



M/X/M

The constant-current source stops charging once the voltage across the soft-start capacitor reaches 1.8V (Figure 5).

Extended Current Limit (MAX1842)

For applications requiring occasional short bursts of high output current (up to 2.7A), the MAX1842 provides a higher current-limit threshold. When using the MAX1842, choose external components capable of withstanding its higher peak current limit.

The MAX1842 is capable of delivering large output currents for limited durations, and its thermal characteristics allow it to operate at continuously higher output currents. Figure 6 shows its maximum recommended continuous output current versus ambient temperature. Figure 7 shows the maximum recommended burst current versus the output current duty cycle at high temperatures.

Figure 7 assumes that the output current is a square wave with a 100Hz frequency. The duty cycle is defined as the duration of the burst current divided by the period of the square wave. This figure shows the limitations for continuous bursts of output current.

Note that if the thermal limitations of the MAX1842 are exceeded, it will enter thermal shutdown to prevent destructive failure.

#### **Frequency Variation with Output Current**

The operating frequency of the MAX1742/MAX1842 is determined primarily by toFF (set by RTOFF), VIN, and VOUT as shown in the following formula:

 $f_{PWM} = (V_{IN} - V_{OUT} - V_{PMOS}) / [t_{OFF} (V_{IN} - V_{PMOS} + V_{NMOS})]$ 

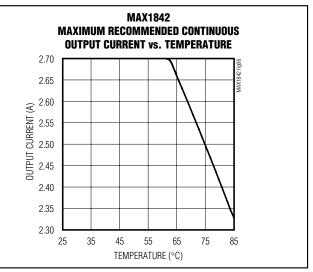
However, as the output current increases, the voltage drop across the NMOS and PMOS switches increases and the voltage across the inductor decreases. This causes the frequency to drop. The change in frequency can be approximated with the following formula:

 $\Delta f_{PWM} = -I_{OUT} \times R_{PMOS} / (V_{IN} \times t_{OFF})$ 

where  $\mathsf{R}_{PMOS}$  is the resistance of the internal MOSFETs (90m $\Omega$  typ).

#### **Circuit Layout and Grounding**

Good layout is necessary to achieve the MAX1742/ MAX1842s' intended output power level, high efficiency, and low noise. Good layout includes the use of a ground plane, careful component placement, and correct routing of traces using appropriate trace widths. The following points are in order of decreasing importance:





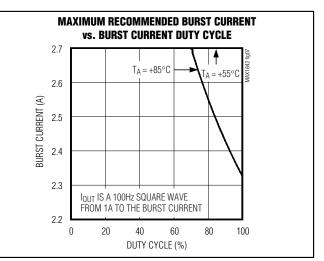


Figure 7. MAX1842 Maximum Recommended Burst Current vs. Burst Current Duty Cycle

- 1) Minimize switched-current and high-current ground loops. Connect the input capacitor's ground, the output capacitor's ground, and PGND. Connect the resulting island to GND at only one point.
- Connect the input filter capacitor less than 5mm away from IN. The connecting copper trace carries large currents and must be at least 1mm wide, preferably 2.5mm.

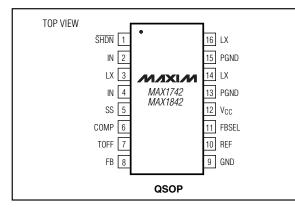


- 3) Place the LX node components as close together and as near to the device as possible. This reduces resistive and switching losses as well as noise.
- 4) A ground plane is essential for optimum performance. In most applications, the circuit is located on a multilayer board, and full use of the four or more layers is recommended. Use the top and bottom layers for interconnections and the inner layers for an uninterrupted ground plane. Avoid large AC currents through the ground plane.

## Chip Information

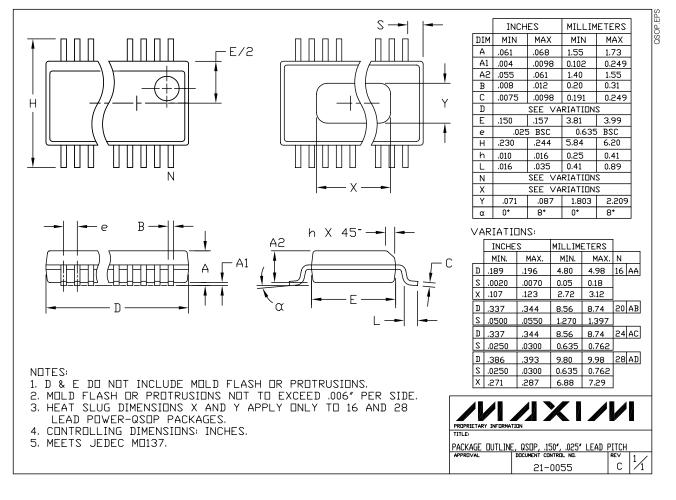
TRANSISTOR COUNT: 3662

# \_\_Pin Configuration



## **Package Information**

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



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Printed USA

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16

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